

Disclaimer

The solution at hand was written in the course of the respective class at the University of Bonn. If not stated differently on top of the first page or the following website, the solution was prepared and handed in solely by me, Marvin Zanke. Anything in a different color than the ball pen blue is usually a correction that I or a tutor made. For more information and all my material, check:

<https://www.physics-and-stuff.com/>

I raise no claim to correctness and completeness of the given solutions! This equally applies to the corrections mentioned above.

This work by [Marvin Zanke](#) is licensed under a [Creative Commons Attribution-NonCommercial-ShareAlike 4.0 International License](#).

29.11.2017 Group theory Exercise 6

Marvin Zanka

H6.1

(1) Representation ρ on L (with dimension d) of a group G is irreducible if it only has the invariant subspaces L and $\{0\}$.
Want to show: irrep of an abelian group \rightarrow one-dimensional

$$\rho(g_1)\rho(g_2) = \rho(g_1g_2) = \rho(g_2g_1) = \rho(g_2)\rho(g_1) \\ \forall g_1, g_2 \in G$$

$$\rho(g)\rho(g') = \rho(g')\rho(g) \quad \forall g, g' \in G$$

Schur's
lemma

$$\rho(g') = \lambda g' \mathbb{1} \quad \forall g' \in G$$

second + because the matrix relate same reps matrices.
If we had a representation with $d > 1$, it would be reducible, as $\rho(g) = \lambda g \mathbb{1}_d$ consists of d irreducible representations. 4p

(2) Cyclic group $G_n = \langle c \mid c^n = e \rangle$ with order n is an abelian group. Every irreducible repr. is thus one-dimensional (see (1)). As we want our repr. to be unitary, it must hold that $\rho(g)^* = \rho(g)^{-1}$ and thus $|\rho(g)|^2 = 1$. It can thus be written as an exponential function in the complex numbers. We want it to fulfill $\rho(e) = \rho(c^n) = (\rho(c))^n$ and thus $\rho(c) = e^{2\pi i \frac{\ell-1}{n}}$ with $\ell = 1, \dots, n$ the roots of unity.

It follows that

$$\rho(c^m) = (\rho(c))^m = e^{2\pi i m \frac{\ell-1}{n}}, \quad m = 1, \dots, n$$

Set of all unitary irrep.

$\ell \neq 1$? trivial mapping?

Why 6-dim?
 6x6 matrices
 or 6 matrices?

H6.2

6-dimensional space of polynomials of degree 2 in (x,y) .

$$f(x,y) = a_1 + a_2x + a_3y + a_4x^2 + a_5xy + a_6y^2$$

$$D(c_1) = \mathbb{1}, \quad D(b) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad D(c) = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}$$

$$D(c^2) = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{pmatrix}$$

$$\rightarrow D(c_1)^{-1} = \mathbb{1}, \quad D(b)^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad D(c)^{-1} = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{pmatrix}$$

$$D(c^2)^{-1} = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}$$

Basis: $f_1(x,y) = 1, f_2(-) = x, f_3(-) = y$
 $f_4(-) = x^2, f_5(-) = xy, f_6(-) = y^2$

Representation for $D(b)$: $D(b)^{-1} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ -y \end{pmatrix}$

$$\begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T \xrightarrow{D(b)} \begin{pmatrix} f_1(D(b)^{-1}x) \\ f_2(\quad) \\ f_3(\quad) \\ f_4(\quad) \\ f_5(\quad) \\ f_6(\quad) \end{pmatrix}^T = \begin{pmatrix} f_1 \\ f_2 \\ -f_2 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T$$

$$\begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$D_b(b)$

Representation for $D(c)$: $D(c)^{-1} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1/2x + \sqrt{3}/2y \\ -\sqrt{3}/2x - 1/2y \end{pmatrix} +$

$$\begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T \xrightarrow{D(c)} \begin{pmatrix} f_1(D(c)^{-1}x) \\ f_2(D(c)^{-1}y) \\ f_3(\quad) \\ f_4(\quad) \\ f_5(\quad) \\ f_6(\quad) \end{pmatrix}^T = \begin{pmatrix} f_1 \\ -1/2f_2 + \sqrt{3}/2f_3 \\ -\sqrt{3}/2f_2 - 1/2f_3 \\ 1/4f_4 - \sqrt{3}/2f_5 + 3/4f_6 \\ \sqrt{3}/4f_4 - 1/2f_5 - \sqrt{3}/4f_6 \\ 3/4f_4 + \sqrt{3}/2f_5 + 1/4f_6 \end{pmatrix}^T$$

Why only 1-
 and 2-dim.
 repr.?

$$= \begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T \underbrace{\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 & 0 & 0 \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{4} & \frac{\sqrt{3}}{4} & \frac{3}{4} \\ 0 & 0 & 0 & -\frac{\sqrt{3}}{4} & -\frac{1}{4} & \frac{\sqrt{3}}{4} \\ 0 & 0 & 0 & \frac{3}{4} & -\frac{\sqrt{3}}{4} & \frac{1}{4} \end{pmatrix}}_{D_6(c)} +$$

Representation for $D_6(c^2)$: $D_6(c^2)^{-1} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -\frac{1}{2}x - \frac{\sqrt{3}}{2}y \\ \frac{\sqrt{3}}{2}x - \frac{1}{2}y \end{pmatrix}$

$$\begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T \xrightarrow{D_6(c)} \begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix} \begin{pmatrix} (D_6(c)^{-1} \vec{x}) \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{pmatrix}^T = \begin{pmatrix} f_1 \\ -\frac{1}{2}f_2 - \frac{\sqrt{3}}{2}f_3 \\ \frac{\sqrt{3}}{2}f_2 - \frac{1}{2}f_3 \\ \frac{1}{4}f_4 + \frac{\sqrt{3}}{4}f_5 + \frac{3}{4}f_6 \\ -\frac{\sqrt{3}}{4}f_4 - \frac{1}{4}f_5 + \frac{\sqrt{3}}{4}f_6 \\ \frac{3}{4}f_4 - \frac{\sqrt{3}}{2}f_5 + \frac{1}{4}f_6 \end{pmatrix}^T$$

$$= \begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{pmatrix}^T \underbrace{\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} & 0 & 0 & 0 \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{4} & -\frac{\sqrt{3}}{4} & \frac{3}{4} \\ 0 & 0 & 0 & \frac{\sqrt{3}}{4} & -\frac{1}{4} & -\frac{\sqrt{3}}{4} \\ 0 & 0 & 0 & \frac{3}{4} & \frac{\sqrt{3}}{4} & \frac{1}{4} \end{pmatrix}}_{D_6(c^2)}$$

$$\rightarrow D_6(bc) = D_6(b) D_6(c) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 & 0 & 0 \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{4} & \frac{\sqrt{3}}{4} & \frac{3}{4} \\ 0 & 0 & 0 & \frac{\sqrt{3}}{4} & -\frac{1}{4} & -\frac{\sqrt{3}}{4} \\ 0 & 0 & 0 & \frac{3}{4} & \frac{\sqrt{3}}{4} & \frac{1}{4} \end{pmatrix}$$

$$D_6(bc^2) = D_6(b) D_6(c^2) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} & 0 & 0 & 0 \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{4} & \frac{\sqrt{3}}{4} & \frac{3}{4} \\ 0 & 0 & 0 & -\frac{\sqrt{3}}{4} & -\frac{1}{4} & -\frac{\sqrt{3}}{4} \\ 0 & 0 & 0 & \frac{3}{4} & \frac{\sqrt{3}}{4} & \frac{1}{4} \end{pmatrix}$$

We can now decompose the reducible representation as follows:

$$D_6(e) = \begin{pmatrix} D_6^{(4)}(e) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(e) & 0 & 0 & 0 \\ 0 & 0 & D_6^{(3)}(e) & 0 & 0 \\ 0 & 0 & 0 & D_6(e) & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{aligned} D_6^{(1)}(e) &= (1) \\ D_6^{(2)}(e) &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ D_6^{(3)}(e) &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{aligned}$$

$$D_6(b) = \begin{pmatrix} D_6^{(1)}(b) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(b) & 0 & 0 & 0 \\ 0 & 0 & D_6^{(3)}(b) & 0 & 0 \\ 0 & 0 & 0 & D_6^{(2)}(b) & 0 \\ 0 & 0 & 0 & 0 & D_6^{(1)}(b) \end{pmatrix} \quad \begin{aligned} D_6^{(1)}(b) &= (1) \\ D_6^{(2)}(b) &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \end{aligned}$$

$$D_6(c) = \begin{pmatrix} D_6^{(1)}(c) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(c) & 0 & 0 & 0 \\ 0 & 0 & D_6^{(3)}(c) & 0 & 0 \\ 0 & 0 & 0 & D_6^{(2)}(c) & 0 \\ 0 & 0 & 0 & 0 & D_6^{(1)}(c) \end{pmatrix} \quad \begin{aligned} D_6^{(1)}(c) &= (1) \\ D_6^{(2)}(c) &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{aligned}$$

$$D_6(c^2) = \begin{pmatrix} D_6^{(1)}(c^2) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(c^2) & 0 & 0 & 0 \\ 0 & 0 & D_6^{(3)}(c^2) & 0 & 0 \\ 0 & 0 & 0 & D_6^{(2)}(c^2) & 0 \\ 0 & 0 & 0 & 0 & D_6^{(1)}(c^2) \end{pmatrix} \quad \begin{aligned} D_6^{(1)}(c^2) &= (1) \\ D_6^{(2)}(c^2) &= \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix} \\ D_6^{(3)}(c^2) &= \begin{pmatrix} 1/4 & \sqrt{3}/4 & 3/4 \\ -\sqrt{3}/2 & -1/2 & \sqrt{3}/2 \\ 3/4 & -\sqrt{3}/4 & 1/4 \end{pmatrix} \end{aligned}$$

$$D_6(c^3) = \begin{pmatrix} D_6^{(1)}(c^3) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(c^3) & 0 & 0 & 0 \\ 0 & 0 & D_6^{(3)}(c^3) & 0 & 0 \\ 0 & 0 & 0 & D_6^{(2)}(c^3) & 0 \\ 0 & 0 & 0 & 0 & D_6^{(1)}(c^3) \end{pmatrix} \quad \begin{aligned} D_6^{(1)}(c^3) &= (1) \\ D_6^{(2)}(c^3) &= \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{pmatrix} \end{aligned}$$

$$D_6^{(3)}(c^3) = \begin{pmatrix} 1/4 & -\sqrt{3}/4 & 3/4 \\ \sqrt{3}/2 & -1/2 & -\sqrt{3}/2 \\ 3/4 & \sqrt{3}/4 & 1/4 \end{pmatrix}$$

Why can we use the theorem already for the subspaces $D_6^{(1)}$, $D_6^{(2)}$ etc?
 e. Why can we split into $D_6^{(1)}(c)$ and then consider each for itself?

$$D_6(bc) = \begin{pmatrix} D_6^{(1)}(bc) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(bc) & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & D_6^{(3)}(bc) & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$D_6^{(1)}(bc) = (1)$$

$$D_6^{(2)}(bc) = \begin{pmatrix} -\sqrt{2} & -\sqrt{3}/2 \\ -\sqrt{3}/2 & \sqrt{2} \end{pmatrix}$$

$$D_6^{(3)}(bc) = \begin{pmatrix} 1/4 & \sqrt{3}/4 & 3/4 \\ \sqrt{3}/2 & 1/2 & -\sqrt{3}/2 \\ 3/4 & -\sqrt{3}/4 & 1/4 \end{pmatrix}$$

+

$$D_6(bc^2) = \begin{pmatrix} D_6^{(1)}(bc^2) & 0 & 0 & 0 & 0 \\ 0 & D_6^{(2)}(bc^2) & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & D_6^{(3)}(bc^2) & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$D_6^{(1)}(bc^2) = (1)$$

$$D_6^{(2)}(bc^2) = \begin{pmatrix} -\sqrt{2} + \sqrt{3}/2 & \\ \sqrt{3}/2 & \sqrt{2} \end{pmatrix}$$

$$D_6^{(3)}(bc^2) = \begin{pmatrix} 1/4 & \sqrt{3}/4 & 3/4 \\ -\sqrt{3}/2 & 1/2 & \sqrt{3}/2 \\ 3/4 & -\sqrt{3}/4 & 1/4 \end{pmatrix}$$

Check by matrix multiplication.

As the dimension of the representation $D_6^{(1)}(g)$ is equal to 1, it has to be an irreducible representation and thus $L_1 = \langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rangle$ is an invariant subspace.

$$\begin{pmatrix} 1/4 & -\sqrt{3}/4 & 3/4 \\ -\sqrt{3}/2 & 1/2 & \sqrt{3}/2 \\ 3/4 & \sqrt{3}/4 & 1/4 \end{pmatrix}$$

To check whether the other representations are irreducible, we make use of the theorem that $\frac{1}{|G|} \sum_{g \in G} |\chi(g)|^2 = 1$ for irreducible representations, where $\chi(g) = \text{Tr}(D(g))$

$$D_6^{(2)} = \frac{1}{6} \left\{ (\text{Tr}(D_6^{(2)}(e)))^2 + \dots - \frac{1}{6} \right\} 2^2 + 0^2 + (-1)^2 + (-1)^2 + 0^2 + 0^2 = 1$$

This can be seen quicker, if one recalls that conjugacy classes (i.e. elements from the same conjugacy class) have the same character and $[e] = \{e\}$, $[c] = \{c, c^2\}$, $[b] = \{b, bc, bc^2\}$

Now consider

$$D_6^{(3)} = \frac{1}{6} \left\{ 9 + 3 \cdot (-1)^2 + 2 \cdot (0)^2 \right\} = 2$$

Thus, $D_6^{(3)}(g)$ is further reducible

+

To find the irreducible representations, we have to construct a new basis. We claim that for the subspace on which $D_6^{(3)}(g)$ acts, the following vectors do the job:

$$\tilde{f}_4 := x^2 + y^2, \quad \tilde{f}_5 := x^2 - y^2, \quad \tilde{f}_6 := xy \quad + 3p$$

It's obviously an equivalent basis, as $f_4 = \frac{1}{2}(\tilde{f}_4 + \tilde{f}_5)$ and $f_5 = \frac{1}{2}(\tilde{f}_4 - \tilde{f}_5)$

then
$$\begin{pmatrix} \tilde{f}_4 \\ \tilde{f}_5 \\ \tilde{f}_6 \end{pmatrix}^T \xrightarrow{D_6(b)} \begin{pmatrix} \tilde{f}_4(R^{-1}x) \\ \tilde{f}_5(R^{-1}x) \\ \tilde{f}_6(R^{-1}x) \end{pmatrix}^T = \begin{pmatrix} \tilde{f}_4 \\ \tilde{f}_5 \\ \tilde{f}_6 \end{pmatrix}^T \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}}_{\tilde{D}_6^{(3)}(b)}$$

$$\begin{pmatrix} \tilde{f}_4 \\ \tilde{f}_5 \\ \tilde{f}_6 \end{pmatrix}^T \xrightarrow{DC(1)} \begin{pmatrix} \tilde{f}_4(R^{-1}x) \\ \tilde{f}_5(R^{-1}x) \\ \tilde{f}_6(R^{-1}x) \end{pmatrix}^T = \begin{pmatrix} x^2 + y^2 \\ -\frac{1}{2}x^2 + \frac{1}{2}y^2 - \sqrt{3}xy \\ \frac{\sqrt{3}}{4}x^2 - \frac{\sqrt{3}}{4}y^2 + \frac{1}{2}xy \end{pmatrix}^T = \begin{pmatrix} \tilde{f}_4 \\ -\frac{1}{2}\tilde{f}_5 - \sqrt{3}\tilde{f}_6 \\ \frac{\sqrt{3}}{4}\tilde{f}_5 - \frac{1}{2}\tilde{f}_6 \end{pmatrix}^T$$

$$= \begin{pmatrix} \tilde{f}_4 \\ \tilde{f}_5 \\ \tilde{f}_6 \end{pmatrix}^T \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{4} \\ 0 & -\sqrt{3} & -\frac{1}{2} \end{pmatrix}}_{\tilde{D}_6^{(3)}(c)}$$

$$\begin{pmatrix} \tilde{f}_4 \\ \tilde{f}_5 \\ \tilde{f}_6 \end{pmatrix}^T \xrightarrow{DC(2)} \begin{pmatrix} \tilde{f}_4(R^{-1}x) \\ \tilde{f}_5(R^{-1}x) \\ \tilde{f}_6(R^{-1}x) \end{pmatrix}^T = \begin{pmatrix} x^2 + y^2 \\ -\frac{1}{2}x^2 + \frac{1}{2}y^2 + \sqrt{3}xy \\ -\frac{\sqrt{3}}{4}x^2 + \frac{\sqrt{3}}{4}y^2 - \frac{1}{2}xy \end{pmatrix}^T = \begin{pmatrix} \tilde{f}_4 \\ -\frac{1}{2}\tilde{f}_5 + \sqrt{3}\tilde{f}_6 \\ -\frac{\sqrt{3}}{4}\tilde{f}_5 - \frac{1}{2}\tilde{f}_6 \end{pmatrix}^T$$

$$= \begin{pmatrix} \tilde{f}_4 \\ \tilde{f}_5 \\ \tilde{f}_6 \end{pmatrix}^T \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{4} \\ 0 & \sqrt{3} & -\frac{1}{2} \end{pmatrix}}_{\tilde{D}_6^{(3)}(c^2)}$$

$$\Rightarrow \tilde{D}_6^{(3)}(bc) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{4} \\ 0 & \sqrt{3} & \frac{1}{2} \end{pmatrix}, \quad \tilde{D}_6^{(3)}(bc^2) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{4} \\ 0 & -\sqrt{3} & \frac{1}{2} \end{pmatrix}$$

Formal way to derive this new basis?

What if we wrote down f_5 as f_4 and vice versa? no diagonal form!

$$\mapsto \tilde{D}_6^{(3)}(e) = \begin{pmatrix} d_6^{(1)}(e) & 0 & 0 \\ 0 & d_6^{(2)}(e) & 0 \\ 0 & 0 & 0 \end{pmatrix}, d_6^{(1)}(e) = (1), d_6^{(2)}(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\tilde{D}_6^{(3)}(b) = \begin{pmatrix} d_6^{(1)}(b) & 0 & 0 \\ 0 & d_6^{(2)}(b) & 0 \\ 0 & 0 & 0 \end{pmatrix}, d_6^{(1)}(b) = (1), d_6^{(2)}(b) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\tilde{D}_6^{(3)}(c) = \begin{pmatrix} d_6^{(1)}(c) & 0 & 0 \\ 0 & d_6^{(2)}(c) & 0 \\ 0 & 0 & 0 \end{pmatrix}, d_6^{(1)}(c) = (1), d_6^{(2)}(c) = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{4} \\ -\sqrt{3} & -\frac{1}{2} \end{pmatrix}$$

$$\tilde{D}_6^{(3)}(c^2) = \begin{pmatrix} d_6^{(1)}(c^2) & 0 & 0 \\ 0 & d_6^{(2)}(c^2) & 0 \\ 0 & 0 & 0 \end{pmatrix}, d_6^{(1)}(c^2) = (1), d_6^{(2)}(c^2) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{4} \\ \sqrt{3} & -\frac{1}{2} \end{pmatrix}$$

$$\tilde{D}_6^{(3)}(bc) = \begin{pmatrix} d_6^{(1)}(bc) & 0 & 0 \\ 0 & d_6^{(2)}(bc) & 0 \\ 0 & 0 & 0 \end{pmatrix}, d_6^{(1)}(bc) = (1), d_6^{(2)}(bc) = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{4} \\ \sqrt{3} & \frac{1}{2} \end{pmatrix}$$

$$\tilde{D}_6^{(3)}(bc^2) = \begin{pmatrix} d_6^{(1)}(bc^2) & 0 & 0 \\ 0 & d_6^{(2)}(bc^2) & 0 \\ 0 & 0 & 0 \end{pmatrix}, d_6^{(1)}(bc^2) = (1), d_6^{(2)}(bc^2) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{4} \\ -\sqrt{3} & \frac{1}{2} \end{pmatrix}$$

All in all, we have the invariant subspaces:

$$S_1 = \langle f_1 \rangle = \langle 1 \rangle, S_2 = \langle f_2, f_3 \rangle = \langle x, y \rangle$$

$$S_3 = \langle \tilde{f}_4 \rangle = \langle x^2 + y^2 \rangle, S_4 = \langle \tilde{f}_5, \tilde{f}_6 \rangle = \langle x^2 - y^2, xy \rangle$$

Did I really choose the correct way of multiplying the basis (from the left) now? And also considered the $\mathbb{R}^T \times$ stuff correctly? Is there a formal way to find the new basis

$$\tilde{f}_4 = x^2 + y^2, \tilde{f}_5 = \text{---} ?$$

- yes
- orthogonalization of matrix?
but it is not easier!

19p \rightarrow 95%. h.h.