

Disclaimer

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21.11.2012 Group Theory Exercise 5

A.5.1

(1) $G/N = \{gN \mid g \in G\}$

$D^{G/N}$ a representation of this quotient group, i.e. $D^{G/N}(gN)$ on L .

Define $D^G(g) := D^{G/N}(gN)$.

This obviously acts on L as well and it forms a group if $D^{G/N}(gN)$ forms a group.

Furthermore: $D^G(g_1 g_2) = D^{G/N}(g_1 g_2 N) \stackrel{\text{Det. of multiplication of cosets}}{=} D^{G/N}(g_1 N g_2 N) = D^{G/N}(g_1 N) D^{G/N}(g_2 N) = D^G(g_1) D^G(g_2)$

(2) Consider a faithful representation of G , $D \equiv D^G$, then

a) $g \mapsto D(g)^t$

$\mapsto D(g_1 g_2)^t = (D(g_1) D(g_2))^t = D(g_2)^t D(g_1)^t \neq D(g_1)^t D(g_2)^t$ as not abelian

\Rightarrow no representation

b) $g \mapsto (D(g^{-1}))^t$

$\mapsto D(g_1 g_2^{-1})^t = D(g_2^{-1} g_1^{-1})^t = (D(g_2^{-1}) D(g_1^{-1}))^t = D(g_1^{-1})^t D(g_2^{-1})^t$

\Rightarrow is a representation

c) $g \mapsto \det(D(g))$

$\mapsto \det(D(g_1 g_2)) = \det(D(g_1) D(g_2)) = \det(D(g_1)) \det(D(g_2))$

\Rightarrow is a representation

d) $g \mapsto \text{Tr}(D(g))$

$\mapsto \text{Tr}(D(g_1 g_2)) = \text{Tr}(D(g_1) D(g_2)) \stackrel{\text{in gen.}}{\neq} \text{Tr}(D(g_1)) \text{Tr}(D(g_2))$

\Rightarrow no representation

Group prop. have to be shown? Why does it even have to be a group? $D^{G/N}$ already a representation and thus group? Why need faithful?

More formal way? Why show $O(g) = D(g)^t$ $O(g_1 g_2) = D(g_2) D(g_1)$ \mapsto define new $D'(g) = D(g)^t$

A5-2 Define $\langle v, w \rangle = \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)v, D^g(g)w \rangle_0$, with $\langle \cdot, \cdot \rangle_0$ Scalar Product

Need to show: $\bullet \langle u, v \rangle = \langle v, u \rangle^*$, $\bullet \langle u, v+w \rangle = \langle u, v \rangle + \langle u, w \rangle$

$\bullet \langle u, \alpha v \rangle = \alpha \langle u, v \rangle$, $\bullet \langle u, u \rangle \geq 0 \forall u \neq 0$, $\bullet \langle u, u \rangle = 0$ iff $u = 0$

Why define different scalar product? use it later in lecture as "group" product?

Pull α out of $D^g(g)$?

$$\begin{aligned} \bullet \langle v, w \rangle &= \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)v, D^g(g)w \rangle_0 \\ \langle \cdot, \cdot \rangle_{SP} &= \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)w, D^g(g)v \rangle_0^* \\ &= \left(\frac{1}{|G|} \sum_{g \in G} \langle D^g(g)w, D^g(g)v \rangle_0 \right)^* = \langle w, v \rangle^* \end{aligned}$$

$$\begin{aligned} \bullet \langle u, v+w \rangle &= \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)u, D^g(g)(v+w) \rangle_0 \\ &= \frac{1}{|G|} \sum_{g \in G} (\langle D^g(g)u, D^g(g)v \rangle_0 + \langle D^g(g)u, D^g(g)w \rangle_0) \\ &= \langle u, v \rangle + \langle u, w \rangle \end{aligned}$$

$$\begin{aligned} \bullet \langle u, \alpha v \rangle &= \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)u, D^g(g)(\alpha v) \rangle_0 \\ &= \frac{1}{|G|} \sum_{g \in G} \alpha \langle D^g(g)u, D^g(g)v \rangle_0 = \alpha \langle u, v \rangle \end{aligned}$$

$$\bullet \langle u, u \rangle = \frac{1}{|G|} \sum_{g \in G} \underbrace{\langle D^g(g)u, D^g(g)u \rangle_0}_{\substack{> 0 \text{ for } D^g(g)u > 0 \\ = 0 \text{ for } D^g(g)u = 0}}$$

$\begin{cases} > 0 \text{ for } u \neq 0 \\ = 0 \text{ for } u = 0 \end{cases} \leftarrow D^g(g) \text{ preserves group structure (unique inverse element)}$

$$D^g(g)v = 0 \forall g \in G \Rightarrow v = D^{-1}(g)0 = 0$$

If $D^g(g)$ Unitary:

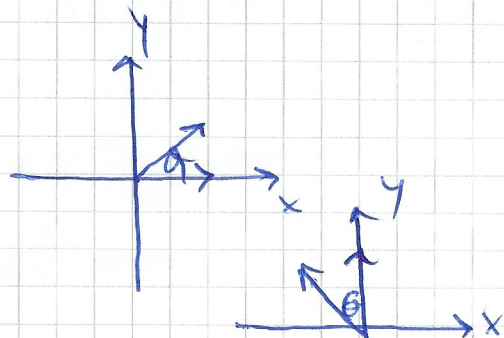
$$\begin{aligned} \langle v, w \rangle &= \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)v, D^g(g)w \rangle_0 = \frac{1}{|G|} \sum_{g \in G} \langle D^g(g)^{\dagger} D^g(g)v, w \rangle_0 \\ &= \frac{1}{|G|} \sum_{g \in G} \langle v, w \rangle_0 = \frac{|G|}{|G|} \langle v, w \rangle_0 = \langle v, w \rangle_0 \end{aligned}$$

A5.3

$$(1) D_3 = \langle c, b \mid c^3 = e, b^2 = e, (bc)^2 = e \rangle$$

We need rotations by $\theta = 120^\circ$ and a reflection at some plane (let's say the x -axis)

$$\begin{aligned} \mapsto \begin{pmatrix} 1 \\ 0 \end{pmatrix} &\mapsto \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \\ \begin{pmatrix} 0 \\ 1 \end{pmatrix} &\mapsto \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix} \end{aligned}$$



$$\mapsto \begin{pmatrix} x \\ y \end{pmatrix} \mapsto R \begin{pmatrix} x \\ y \end{pmatrix} \text{ with } R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\mapsto D(c) = R$$

$$D(c \cdot c) = R^2 = D(c) D(c) \text{ (trigonometry)}$$

$$D(c \cdot c \cdot c) = 1$$

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x \\ -y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$D(b) = M$$

$$D(b \cdot b) = M^2 = 1$$

$$D(c) = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}$$

$$D(c^2) = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{pmatrix}$$

$$D(bc) := D(b) D(c) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$= \begin{pmatrix} \cos \theta & -\sin \theta \\ -\sin \theta & -\cos \theta \end{pmatrix}, D(bc) = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ -\sqrt{3}/2 & 1/2 \end{pmatrix}$$

$$D(bc^2) = D(b) D(c) D(c) = M R^2$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos 2\theta & -\sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{pmatrix}, D(bc^2) = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ \sqrt{3}/2 & 1/2 \end{pmatrix}$$

$$= \begin{pmatrix} \cos 2\theta & -\sin 2\theta \\ -\sin 2\theta & -\cos 2\theta \end{pmatrix}$$

$$\chi(c) = \text{Tr}(D(c)) = -1, \chi(c^2) = -1, \chi(e) = 2$$

$$\chi(b) = 0, \chi(bc) = 0, \chi(bc^2) = 0$$

What exactly do we further have to prove? \mapsto constance like this

The conjugacy classes:

$$\tilde{Z} = g c g^{-1} \text{ for } g = c^u \text{ or } g = b c^u$$

$$\rightarrow c^u c c^{-u} = c \quad \rightarrow C \text{ itself} \quad \Rightarrow \{c, c^2\}$$

$$\rightarrow b c^u c c^{-u} b = b c b = c^{-1} = c^2$$

$$g b g^{-1} \rightarrow c^u b c^{-u} = b c^{3-2u} = b c^{-2u}$$

$$\rightarrow b c^u b c^{-u} b = c^{3+2u} c^{-u} b = b c^{3+2u} = b c^{2u}$$

$$\Rightarrow \{b, b c, b c^2\}$$